

Quick Recap

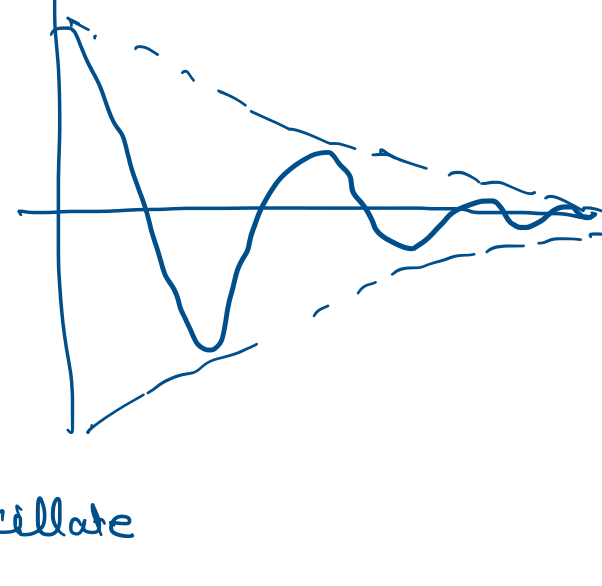
$$\ddot{z} + \gamma \dot{z} + \omega_0^2 z = 0$$

Ansatz: $z(t) = C e^{\alpha t} \Rightarrow \alpha = -\frac{\gamma}{2} \pm \frac{1}{2} \sqrt{\gamma^2 - 4\omega_0^2}$

① Lightly / Under damped ($\gamma < 2\omega_0$)

$$\alpha = -\frac{\gamma}{2} \pm i\omega_u \quad ; \quad \omega_u = \omega_0 \sqrt{1 - \frac{\gamma^2}{4\omega_0^2}}$$

$$\therefore z(t) = A e^{-\gamma t/2} \cos(\omega_u t + \phi)$$



② Overdamp ($\gamma > 2\omega_0$)

$$z(t) = C_1 e^{-\alpha_1 t} + C_2 e^{-\alpha_2 t}$$

$$\alpha_{1/2} = \frac{\gamma}{2} \pm \frac{1}{2} \sqrt{\gamma^2 - 4\omega_0^2}$$

$$\alpha_1 > \alpha_2 > 0$$

} Never Oscillate

③ Critical damping ($\gamma = 2\omega_0$)

$$z(t) = (C_1 + C_2 t) e^{-\gamma t/2} = (C_1 + C_2 t) e^{-\omega_0 t}$$

↳ no oscillations

[fastest return to equilibrium]

e.g. door or car shock absorbers

④ Very lightly damped.

$$\gamma \ll 2\omega_0$$

$$\omega_u = \omega_0 \left(1 - \frac{1}{2} \frac{\gamma^2}{4\omega_0^2} + O\left(\frac{\gamma^4}{\omega_0^4}\right) \right)$$

$$\approx \omega_0 \left(1 - \frac{\gamma^2}{8\omega_0^2} \right)$$

∴ upto linear order

$$\omega_u \approx \omega_0$$

As before, we will try to look at the energy picture too.

$$E = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} k x^2 \quad \left. \begin{array}{l} \text{am i missing a friction/damping} \\ \text{term?} \end{array} \right\}$$

We just don't have conserved energy anymore.

$$\frac{dE}{dt} = \frac{1}{2} m (2\dot{x}\ddot{x}) + \frac{1}{2} k (2x\dot{x})$$

$$= \dot{x} (m\ddot{x} + kx) \quad \left[\text{Recall that for } \gamma=0, m\ddot{x} + kx = 0 \right]$$

$$= -b\dot{x}^2 < 0 \quad \left[\text{But we do have } m\ddot{x} + b\dot{x} + kx = 0 \right]$$

↳ loss of energy in system.

You can also see,

$$\frac{dE}{dt} = (-b\dot{x}) \dot{x} = \vec{F}_{\text{damp}} \cdot \vec{v} \quad \left. \begin{array}{l} \text{Power dissipated by damping} \\ \text{force} \end{array} \right\}$$

lets look at more specific cases

lightly damped

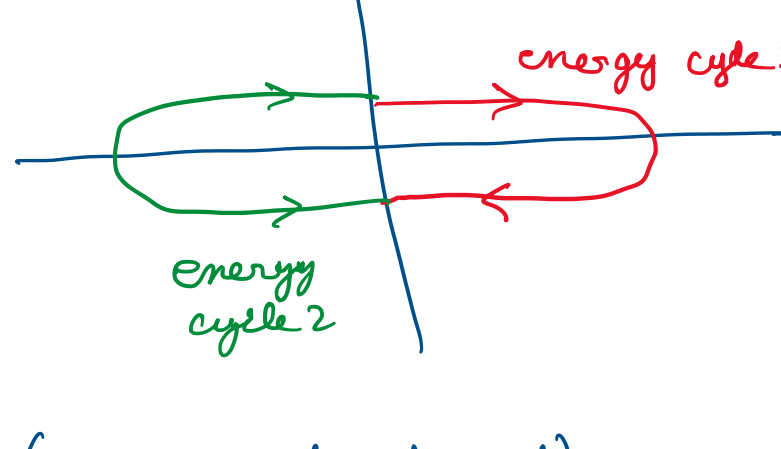
$$E = \frac{1}{2} m v^2 + \frac{1}{2} k x^2$$

$$\text{using } z(t) = A e^{-\gamma t/2} \cos(\omega_u t + \phi)$$

$$E = \frac{1}{2} m A^2 e^{-\gamma t} \left[\frac{\gamma^2}{4} \cos^2(2\omega_u t) + \frac{\gamma \omega_u}{2} \sin(2\omega_u t) + \omega_u^2 \right]$$

↳ Take away energy oscillates at twice the frequency of oscillation.

(How? Why?)



$\gamma \ll 2\omega_0$ (very lightly damped)

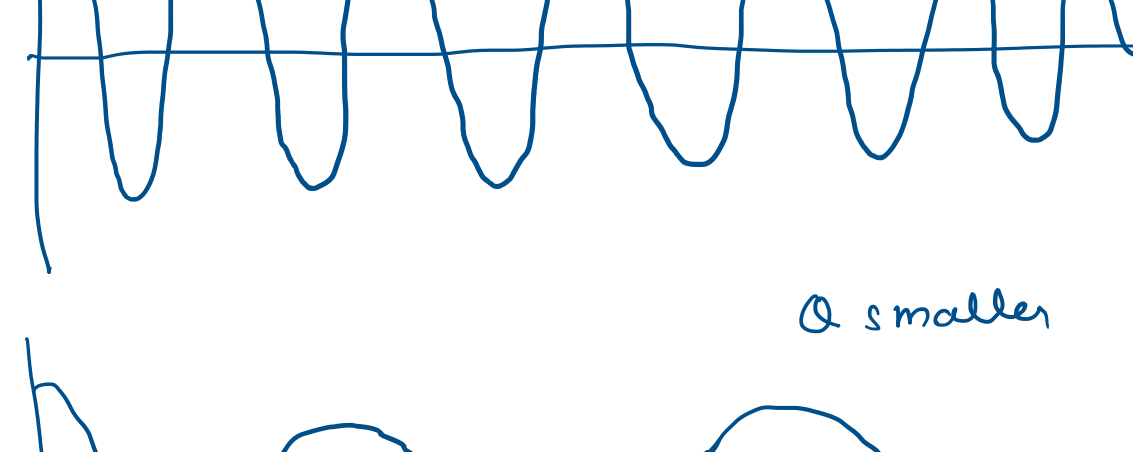
$$\langle E \rangle = \frac{1}{2} m \omega_u^2 A^2 e^{-\gamma t}$$

↳ ignore oscillating term ↳ Energy without damping

lets define some quantities you will encounter

$$Q = \omega_0 / \gamma \quad \left. \begin{array}{l} \text{dimensionless} \\ \text{(its a quick check)} \end{array} \right\}$$

smaller Q
→ dies off quickly
→ oscillates with much longer time period



Q large Very lightly damped

Q smaller

Time period increases

So, for $\gamma \ll 2\omega_0$, by what fraction does amplitude fall after Q cycles?

$$\text{After } Q \text{ cycles: } A_{\text{final}} = A_{\text{init}}$$

$$\omega_u t = 2\pi Q$$

$$\Rightarrow t = \frac{2\pi Q}{\omega_0 / Q} = \frac{2\pi Q^2}{\omega_0}$$

$$\therefore A_{\text{fin}} = e^{-\gamma t/2} A_{\text{init}} = e^{-\pi Q} A_{\text{init}}$$

↳ independent of γ/ω_0
0.043

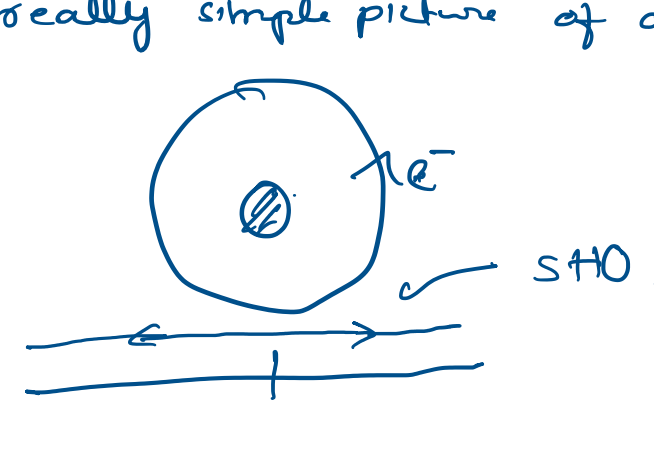
No. of cycles after which amplitude is 4.3% gives us Q.

lets study a special case,

Classical EM: accelerating charges radiate energy
↳ EM wave

$$\text{We know from EM } \frac{dE}{dt} = \frac{K e^2 a^2}{c^3} \quad \left. \begin{array}{l} \text{power radiated} \end{array} \right\}$$

lets look at a really simple picture of atom: (consider very slightly damped)



For 1 cycle
 $x = A \sin(\omega t)$ for 1 coordinate
 $a = \ddot{x} = -\omega^2 x$

How much energy is lost in each cycle?

$$\Delta E = \int_0^{2\pi/\omega} \frac{K e^2 a^2}{c^3} dt = \frac{K e^2 \omega^4 A^2}{c^3} \int_0^{2\pi/\omega} \sin^2 \omega t dt$$

↳ energy lost in each cycle

What is the quality factor for the atom?

$$\frac{\Delta E}{E_{\text{ini}}} = -\gamma T \quad \text{from } \langle E \rangle = \frac{1}{2} m \omega_u^2 A^2 e^{-\gamma t}$$

↳ linear expansion

$$\text{plug in } \Delta E, E_{\text{ini}} = \frac{1}{2} m \omega^2 A^2 \text{ \& } T = 2\pi/\omega$$

to get γ

$$\text{Now } \gamma = 1/Q$$

$$\text{or } Q = \omega_0 / \gamma$$

So if a e^- oscillates at a freq of green color ($\lambda \sim 500 \text{ nm}$) then we get $T = 10^{-8} \text{ secs}$. So how does the universal remain stable?

→ learn in Ph2b.

Driven damped harmonic oscillator

$$\ddot{x} + \gamma \dot{x} + \omega_0^2 x = \frac{F_0}{m} \cos \omega t$$

↳ natural freq, driving freq, generalized force

Two behaviours
↳ ① Transient → damping and natural frequencies all die out
↳ ② Steady state → only driving forces remain (t → ∞)

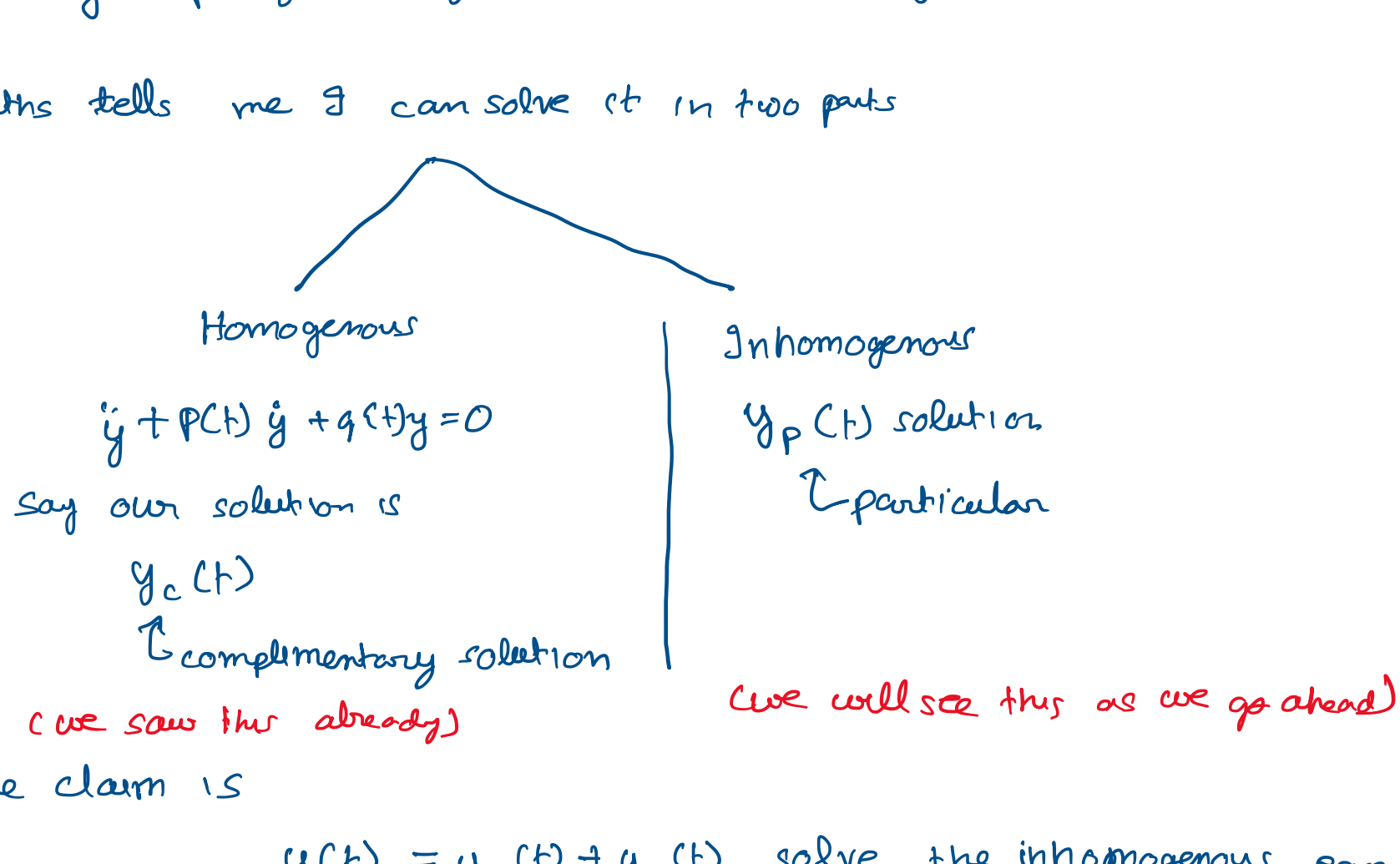
We will solve for this next week.

But lets look at some diff eqs. first

Inhomogeneous Diff Equation

$$\ddot{y} + p(t)\dot{y} + q(t)y = g(t) \quad \leftarrow \text{most general 2nd order ODE}$$

Maths tells me I can solve it in two parts



So how do find $y_p(t)$ → Guess

$$\text{e.g. } \ddot{y} - 4\dot{y} - 12y = 3e^{5t}$$

$$\text{guess } y_p(t) = A e^{5t}$$

$$25A e^{5t} - 20A e^{5t} - 12A e^{5t} = 3e^{5t}$$

$$\Rightarrow A = -3/7$$

$$\text{e.g. } \ddot{y} - 4\dot{y} - 12y = 2t^3 - t + 3$$

$$\text{guess } y_p(t) = At^3 + Bt^2 + Ct + D \quad \leftarrow \text{for } n\text{th order driving polynomial guess a similar polynomial}$$

Plug & now match order by order

$$\text{e.g. if } g(t) = 5 \cos \omega t$$

$$y_p(t) = A \cos(\omega t) + B \sin(\omega t)$$

This is called method of undetermined coefficients.