

Lecture 12.

We had earlier studied that using Ampere's law,

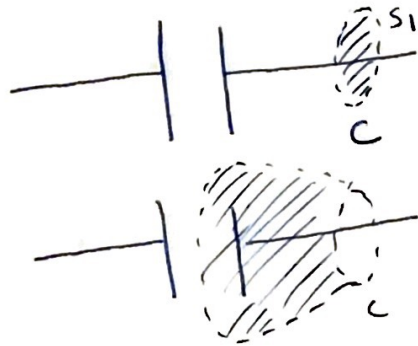
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

Rather,

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 \int_S \vec{J} \cdot d\vec{A}$$

where S is a surface enclosed by C . From our earlier discussions, we had noted that this S can be any surface bounded by C .

Let us consider the following examples,



$$\int \vec{J} \cdot d\vec{A} = I$$

$$\int \vec{J} \cdot d\vec{A} = 0$$

(No current crosses the surface)

$\oint \vec{B} \cdot d\vec{l} = \mu_0 \int \vec{J} \cdot d\vec{A}$ is clearly incorrect. Consequently, the differential version must be too. i.e. $\nabla \times \vec{B} = \mu_0 \vec{J}$ is incorrect.

Further

$\nabla \times \vec{B} = \mu_0 \vec{J}$ holds only for steady currents.

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = 0 = \mu_0 (\vec{\nabla} \cdot \vec{J})$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} \text{ (from continuity equation)}$$

$$\vec{\nabla} \cdot \vec{J} \neq 0 \text{ for changing currents}$$

To make

$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = 0$ (I just need to add a term that has a opposite contribution to $\vec{\nabla} \cdot \vec{J} = 0$)

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} = -\frac{\partial}{\partial t} \underbrace{(\epsilon_0 \vec{\nabla} \cdot \vec{E})}_{\text{from Gauss law}} = -\vec{\nabla} \cdot \epsilon_0 \left(\frac{\partial \vec{E}}{\partial t} \right)$$

$$\therefore \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \text{ solves our problem.}$$

I have a slightly off beat way of looking at this equation. You can decide for yourself if the picture helps.

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \left(\begin{array}{l} \text{electric} \\ \text{field created by changing} \\ \text{magnetic dipole field} \end{array} \right)$$

Similarly

$$\vec{\nabla} \times \vec{B} = (\odot) \frac{\partial \vec{E}}{\partial t} \quad \left(\text{due to charge dipoles} \right)$$

↳ proportionality factor

As charges can exist as monopoles,

$$\vec{\nabla} \times \vec{B} = () \vec{J} + () \frac{\partial \vec{E}}{\partial t}$$

If magnetic monopoles existed,

$$\vec{\nabla} \times \vec{E} = () \vec{B} + () \frac{\partial \vec{B}}{\partial t}$$

↳ current
of magnetic monopoles

Coming back to our initial discussion, the second term appears due to changing current or accumulation of charges.

$$J_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$



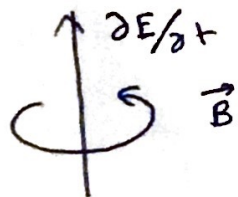
Displacement

Current Density

(Historical term - holds little importance now) ~~current~~ electric field, leading to

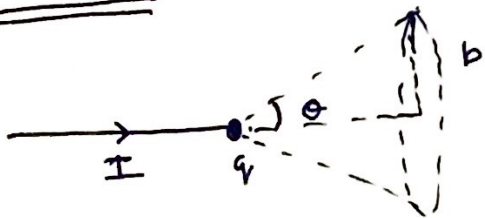
We instead interpret it as changing magnetic field.

(Recollect the similar scenario for Faraday's electric field due to changing magnetic field).



Due to the very small value of ϵ_0 , we shall ignore this term for quasi static cases or slowly varying electric fields.

Problem 1



A half-infinite wire carries current I from negative infinity to origin where it builds up as a point charge q . Consider the circle of radius ' b ' and subtends an angle ' 2θ ' with respect to the charge.

Find $\oint \vec{B} \cdot d\vec{l}$ for this curve.

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \int (\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}) \cdot d\vec{a}$$

$$= [\vec{J} = 0 \text{ through the surface}]$$

$$= \mu_0 \epsilon_0 \int \frac{\partial \vec{E}}{\partial t} \cdot d\vec{a}$$

$$= \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left(\int \vec{E} \cdot d\vec{a} \right)$$

$$[\text{Solid angle} = 2\pi [1 - \cos\theta]]$$

$$= \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left[\frac{q}{\epsilon_0} \frac{2\pi [1 - \cos\theta]}{4\pi} \right]$$

$$= \mu_0 \epsilon_0 \frac{1}{\epsilon_0} \frac{1}{2} [1 - \cos\theta] I$$

$$= \frac{\mu_0}{2} [1 - \cos\theta] I$$

Problem 2

A solenoid of radius 'R' & 'n' turns per unit length has current $I = I_0 \cos(\omega t)$, flowing through it.

1) Calculate B due to the current.

2) Calculate E due to changing \vec{B} .

3) Changing \vec{E} causes \vec{B} . Calculate ΔB^{ind} due to \vec{E} , where

$$\Delta B^{ind} = B^{ind}(\gamma, t) - B(0, t).$$

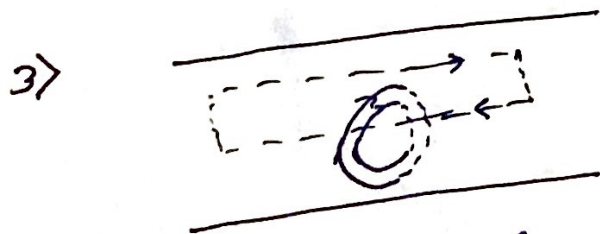
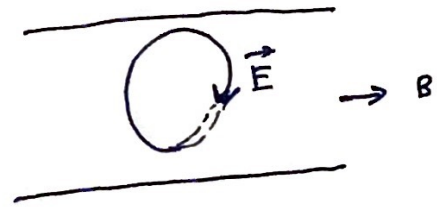
~~4) Show that $\Delta B/B$ is very small for frequencies encountered in daily life.~~

1) $\vec{B} = \mu_0 n I_0 \cos(\omega t)$

2) $\int \vec{E} \cdot d\vec{S} = -\frac{\partial}{\partial t} \int \vec{B} \cdot d\vec{a}$

$$E \times 2\pi r = +\mu_0 n I_0 \omega \sin(\omega t) \pi r^2$$

$$\vec{E} = + \frac{\mu_0 n I_0 \omega r \sin(\omega t)}{2}$$



(I decide the direction already by other side)

$$\int \vec{B} \cdot d\vec{S} = \mu_0 \int (\vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}) \cdot d\vec{a}$$

$$= \mu_0 \int \vec{J} \cdot d\vec{a} + \mu_0 \epsilon_0 \frac{\partial \Phi_E}{\partial t}$$

$$B(0, t) - B(\gamma, t) = \mu_0 \epsilon_0 \frac{\partial \Phi_E}{\partial t}$$

$$-\Delta(B(\gamma, t)) = \mu_0 \epsilon_0 \frac{\mu_0 n I_0 \omega^2 r^2 \cos(\omega t)}{4}$$

$$\Rightarrow \Delta B(\gamma, t) = \frac{\mu_0^2 \epsilon_0 n I_0 \omega^2 r^2 \cos(\omega t)}{4}$$

Problem 3

If magnetic monopoles existed, Maxwell's equations would look like

$$\vec{\nabla} \cdot \vec{E} = \rho_e / \epsilon_0 \quad \vec{\nabla} \cdot \vec{B} = \mu_0 \rho_m$$

$$\vec{\nabla} \times \vec{E} = -\mu_0 \vec{J}_m - \frac{\partial \vec{B}}{\partial t} \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}_e + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

Assume a particle with q_m and no q_e . It passes through a loop wire with self inductance L .

- Write down integral form of Faraday's law from these equations
- Using self inductance, find $\frac{\partial I(t)}{\partial t}$ in the loop.
- Integrate over time and rewrite as total change in variables.
- Assuming that there is no initial current in loop, what current is flowing after the monopole has passed through? (Assume it started arbitrarily far and is again arbitrarily far away).

$$a) \int (\vec{\nabla} \times \vec{E}) \cdot d\vec{A} = -\mu_0 \int \vec{J}_m \cdot d\vec{a} - \int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{a}$$

$$\therefore \oint \vec{E} \cdot d\vec{l} = -\mu_0 I_{enc}^m - \frac{\partial \Phi_B}{\partial t}$$

$$b) \mathcal{E} = -L \frac{dI_e}{dt}$$

$$L \frac{dI_e}{dt} = \mu_0 I_{enc}^m + \frac{\partial \Phi_B}{\partial t}$$

$$c) L \frac{dI_e}{dt} = \mu_0 \frac{\partial Q_{m,enc}(t)}{\partial t} + \frac{\partial \Phi_B(t)}{\partial t}$$

$$L \Delta I = \mu_0 \Delta Q_m + \Delta \Phi_B \Rightarrow \Delta I = \frac{\mu_0}{L} \Delta Q_m + \frac{1}{L} \Delta \Phi_B$$

$$d) \quad \Delta \Phi_B = 0$$

$$\Delta I = \frac{\mu_0 \Delta Q_m}{L}$$

$$\therefore I_g = \frac{\mu_0 q_m}{L}$$