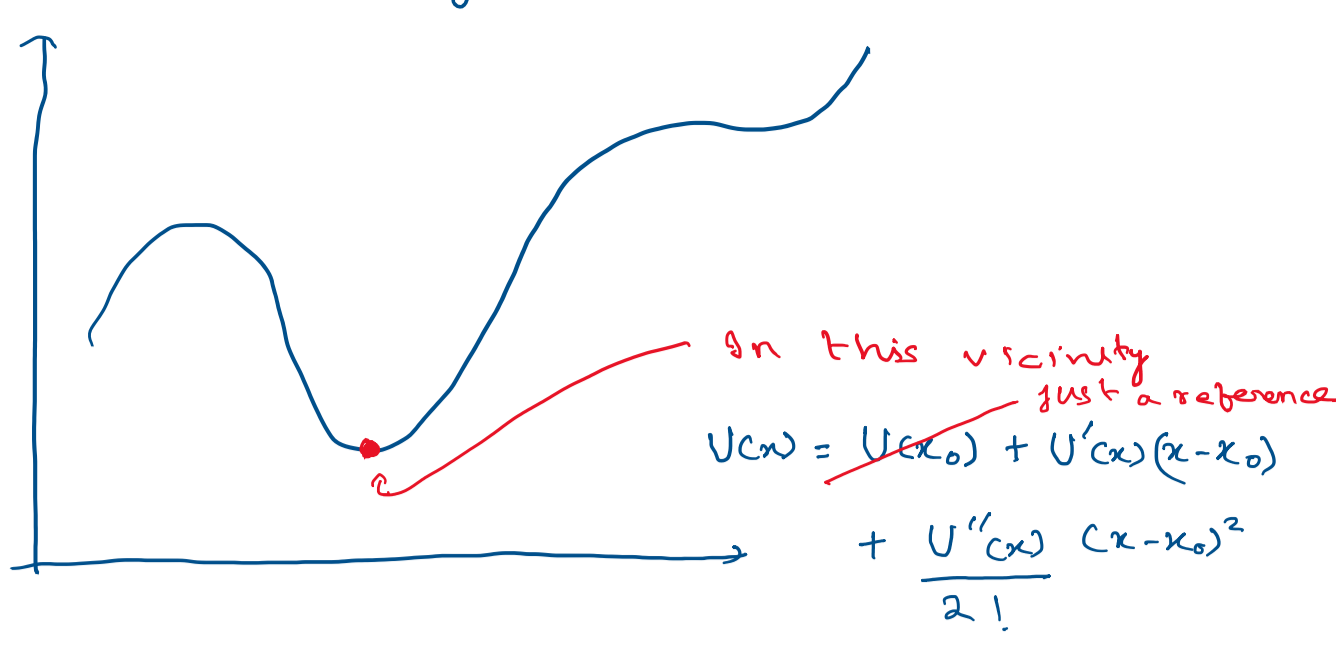


Lecture 12

Sunday, 10 November 2019 11:18 PM

Let us assume any potential function



$$\therefore U(x) \approx \frac{U''(x_0)}{2!} (x-x_0)^2$$

$$\therefore U(x) \approx \frac{1}{2} k (x-x_0)^2$$

All equilibriums come with harmonic potentials.

$$U = \frac{1}{2} kx^2$$

$$F = -\frac{dU}{dx} = -kx$$

$$ma = -kx$$

$$\ddot{x} = -\frac{k}{m}x$$

For any equations of this form

$$x(t) = A \cos(\omega t + \delta) \quad \& \quad \omega = \sqrt{\frac{k}{m}}$$

↑
phase shift

$$\text{or } x(t) = C \cos \omega t + D \sin \omega t$$

$$\text{or } x(t) = E e^{i\omega t} + F e^{-i\omega t}$$

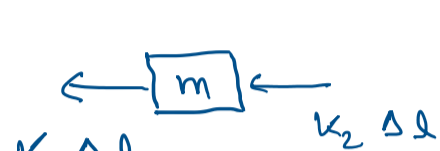
You always need two initial conditions to find out the constants.

Let's apply these to a problem

- 1) Determine the period of small longitudinal oscillations of a body with mass m and values of spring k_1 and k_2 . The friction and the masses of the springs are negligible.



Let the original length be l & change be Δl



$$\therefore \text{Force} = -(k_1 + k_2) \Delta l$$

$$\ddot{x} = -\frac{(k_1 + k_2)}{m} \Delta l$$

$$\therefore \omega = \sqrt{\frac{k_1 + k_2}{m}}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k_1 + k_2}}$$

- 2) A particle of mass m moves due to the force

$\vec{F} = -\alpha m \vec{r}$ where α is a positive constant, \vec{r} is the radius vector of the particle relative to the origin of coordinates. Find the trajectory of its motion if at initial moment $\vec{r} = r_0 \hat{i}$ & $\vec{v} = v_0 \hat{j}$.

$$\vec{F} = -\alpha m \vec{r}$$

$$= -\alpha m (x\hat{i} + y\hat{j})$$

For x

$$F_x = -\alpha m x$$

$$a_x = -\alpha x \Rightarrow \omega_1 = \sqrt{\alpha}$$

$$\therefore x = A \sin(\sqrt{\alpha} t + \phi)$$

$$\text{at } t=0, x = r_0 \text{ \& } v_x = 0$$

$$\therefore r_0 = A \sin \phi$$

$$\& \quad v_x = A\sqrt{\alpha} \cos(\sqrt{\alpha} t + \phi)$$

$$0 = A\sqrt{\alpha} \cos(\phi)$$

$$\therefore \phi = \pi/2$$

$$x = r_0 \sin(\sqrt{\alpha} t + \pi/2)$$

$$= r_0 \cos(\sqrt{\alpha} t)$$

For y

$$F_y = -\alpha m y$$

$$y = B \sin(\sqrt{\alpha} t + \delta)$$

$$\text{at } t=0, y = 0 \text{ \& } v = v_0$$

$$0 = B \sin \delta$$

$$\therefore \delta = 0$$

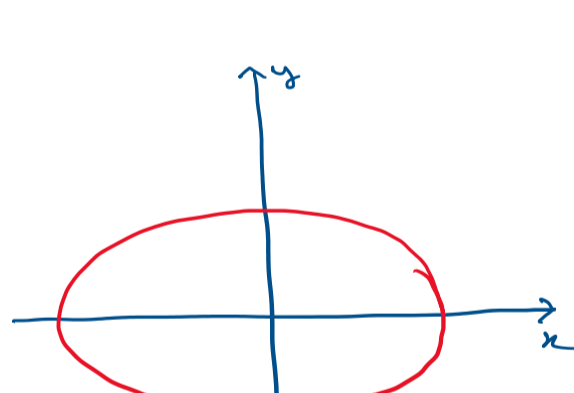
$$v_y = B\sqrt{\alpha} \cos(\sqrt{\alpha} t)$$

$$\Rightarrow v_0 = B\sqrt{\alpha}$$

$$\Rightarrow B = v_0/\sqrt{\alpha}$$

$$y = v_0/\sqrt{\alpha} \sin(\sqrt{\alpha} t)$$

$$\therefore \left(\frac{x}{r_0}\right)^2 + \left(\frac{y}{v_0/\sqrt{\alpha}}\right)^2 = 1$$



Damped Harmonic Oscillator

$$m\ddot{x} = -kx - r\dot{x}$$

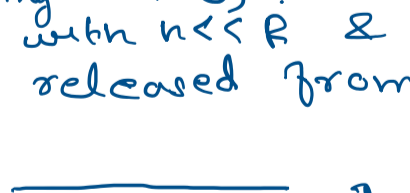
↳ Damping

$$\ddot{x} + \frac{r}{m}\dot{x} + \frac{k}{m}x = 0$$

$$\Rightarrow \ddot{x} + \beta\dot{x} + \omega_0^2 x = 0$$

$$x(t) = C e^{-\beta t/2} \cos(\sqrt{\omega_0^2 - \beta^2/4} t + \delta)$$

- 2) A disc of radius R suspended by a rod between two stationary plates and performs torsional oscillation ($\tau_{restoring} = -b\theta$). The clearance is equal to h , with $h \ll R$ & viscosity is η . Find the $\theta(t)$ if it's released from rest with a twist of θ_0



$$\therefore F_{viscous} = \eta A \frac{dv}{dz}$$

$$= \frac{\eta A v}{h}$$



$$dF = 2 \left[\eta \cdot 2\pi r dr \cdot \frac{\omega r}{h} \right]$$

$$d\tau = -2 \left[\eta \cdot 2\pi r dr \cdot \frac{\omega r}{h} \right] r$$

$$\therefore \tau = -\frac{4\pi\eta\omega}{h} \int r^3 dr$$

$$= -\frac{\pi\eta\omega}{h} R^4$$

$$\therefore \tau_{net} = -b\theta - \frac{\eta\pi\omega R^4}{h}$$

$$\Rightarrow I\ddot{\theta} + \frac{\eta\pi R^4}{h}\dot{\theta} + b\theta = 0$$

$$\Rightarrow \ddot{\theta} + \frac{\eta\pi R^4}{hI}\dot{\theta} + \left(\frac{b}{I}\right)\theta = 0$$

$$\therefore \theta(t) = C e^{-\beta t/2} \cos(\sqrt{\omega_0^2 - \beta^2/4} t + \delta)$$

$$\therefore \text{at } t=0$$

$$\theta_0 = C \cos \delta$$

$$0 = C \sqrt{\omega_0^2 - \beta^2/4} \sin \delta$$

$$\therefore \delta = 0 \text{ \& } c = \theta_0$$

$$\theta(t) = \theta_0 e^{-\beta t/2} \cos(\sqrt{\omega_0^2 - \beta^2/4} t)$$