

\* Angular Momentum for extended body

$$\vec{L} = M(\vec{R}_{CM} \times \vec{v}_{CM}) + I_{CM} \omega_{CM} \hat{z}$$

$\vec{R}_{CM}$ : position of CM  
 $\vec{v}_{CM}$ : velocity of CM  
 $I_{CM}$ : Moment of inertia about axis through CM  
 $\omega_{CM}$ :  $\omega$  about axis passing through CM

\* KE of extended rotating body

$$KE = \frac{1}{2} M v_{CM}^2 + \frac{1}{2} I_{CM} \omega_{CM}^2$$

$v_{CM}$ : velocity of CM  
 $\omega_{CM}$ :  $\omega$  about CM axis

\*  $\perp$  axis theorem

$$I_z = I_x + I_y$$

(Only holds for laminar bodies)  
 $\perp$  passes through body & CM  
 $\perp$  pass  $\perp$  to the body and through CM

\*  $\parallel$  axis theorem

$$I = I_{CM} + M d^2$$

$M$ : Mass of body  
 $d$ : distance from CM to new axis  
 $I_{CM}$ : I about CM  
 $I$ : I about new axis

\*  $\tau = I \alpha$

\* In rolling without slipping

$$v = \omega R$$

$$a = \alpha R$$

\* For SHM, show

$$m \ddot{x} = -kx \quad \text{or} \quad \frac{1}{2} k A^2 = \frac{1}{2} k x^2 + \frac{1}{2} m v^2$$

$$\omega = \sqrt{k/m} \quad \& \quad T = 2\pi/\omega$$

All  $x$  that follow the above relation,

$$x(t) = A \cos(\omega t + \delta)$$

$A$  &  $\delta$  obtained using initial conditions

To solve SHM problems,

- |  |                                     |
|--|-------------------------------------|
| 1) Find eq condition.<br>2) Displace slightly<br>3) Write new eq of motion | 1) Write E<br>2) Equate $dE/dt = 0$ |
|--|-------------------------------------|

\* If  $m \ddot{x} = -kx - \gamma \dot{x}$

$$\ddot{x} + \frac{\gamma}{m} \dot{x} + \frac{k}{m} x = 0$$

$$\Rightarrow \ddot{x} + \beta \dot{x} + \omega_0^2 x = 0$$

$$x(t) = C e^{-\beta t/2} \cos\left(\sqrt{\omega_0^2 - \beta^2/4} t + \delta\right)$$

\* Potential energy in gravity =  $-\frac{GMm}{r}$

\* In Orbit, Energy and Angular Momentum is always conserved.

$$E = \frac{1}{2} m v_r^2 + \frac{1}{2} m v_t^2 - \frac{GMm}{r}$$

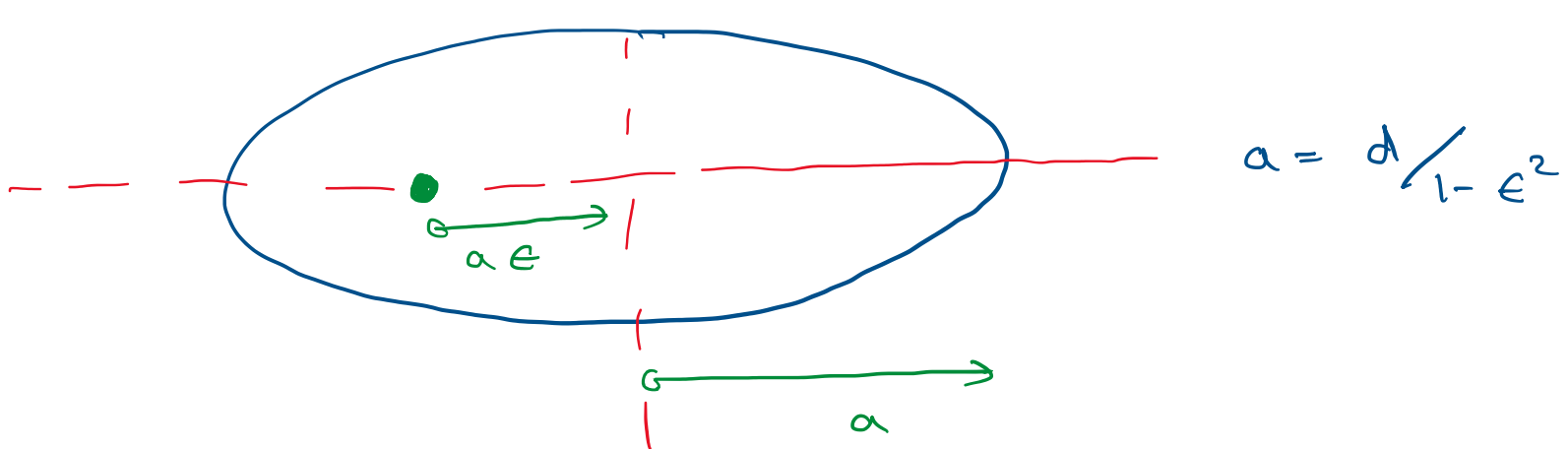
$v_r$ : radial velocity  
 $v_t$ : tangential velocity

$$L = m v_t r$$

Equation of orbit

$$r = \frac{d}{(1 + \epsilon \cos \theta)}$$

$$d = \frac{L^2}{GMm^2} \quad \& \quad \epsilon = \left(1 + \frac{2 E L^2}{G^2 M^2 m^3}\right)^{1/2}$$



$$r_{min} = \frac{d}{1 + \epsilon} = a(1 - \epsilon)$$

$$r_{max} = \frac{d}{1 - \epsilon} = a(1 + \epsilon)$$

For  $E < 0$ , it is bounded / elliptical orbit  
 For  $E > 0$ , it is unbounded / hyperbolic orbit

\*  $T^2 = \frac{4\pi^2}{GM} a^3$   
 $T^2 \propto a^3$  } Kepler's third law